Hydrostatic Pump Repair

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Proportional pressure reducing valve, pilot operated

RE 29279/12.10 Replaces: 01.09

1/14

Types ZDRE; ZDREE

Size 10 Component series 2X Maximum pressure setting 315 bar Maximum flow 80 l/min

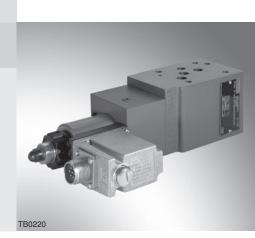


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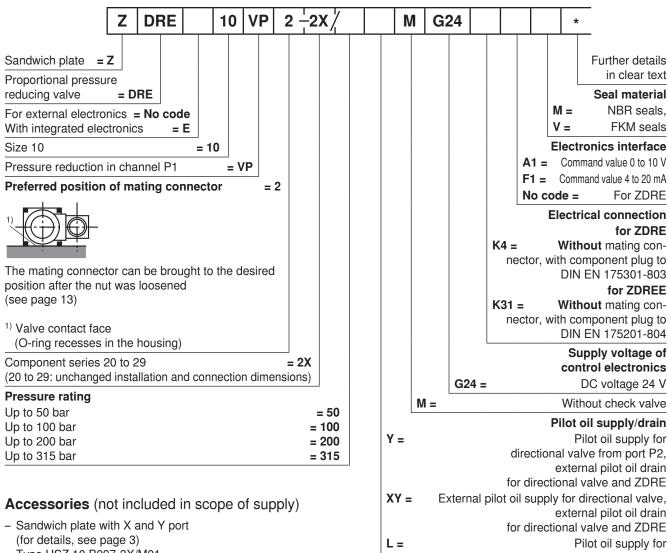
Features Ordering code 3 Symbols 4 Function, section Pilot oil supply for directional valve mounted above 5 Technical data 6 and 7 Electrical connection 8 and 9 Integrated electronics (OBE) of type ZDREE Characteristic curves 10 to 12 Unit dimensions 13

Features

- Pilot operated valve for reducing a system pressure
- Actuation by proportional solenoid, which can be rotated
- 3 Sandwich plate design
- Porting pattern to DIN 24340-A and ISO 4401
- 5 4 pressure ratings
- 7 Valve and control electronics from a single source
 - External control electronics for type ZDRE
 - Linear command value/pressure characteristic curve
 - Integrated electronics (OBE) with type ZDREE, with low manufacturing tolerance of the command value/pressure characteristic curve

Information on available spare parts: www.boschrexroth.com/spc

Ordering code



- Type HSZ 10 B097-3X/M01 Material no.: R900320785
- Subplates to data sheet RE 45054
 - G 535/01 (G3/4), Material no. R900476061
 - G 536/01 (G1), Material no. R900476059
- External control for type ZDRE:
 - Analog amplifier VT-MSPA1-11-1X/V0 of modular design to data sheet RE 30223
 - Digital amplifier VT-VSPD-1-2X/V0/.-0-1 of Euro-card format to data sheet RE 30523
 - Analog amplifier VT-VSPA1-11-1X/V0/0 of Euro-card format to data sheet RE 30100
- Mating connectors (for details, see page 8)
 - For ZDRE: to DIN EN 175301-803, Material no. R901017011
 - For ZDREE: to DIN EN 175201-804, Material no. R900021267 or R900223890

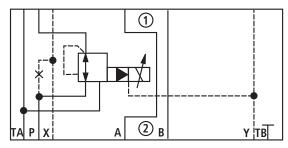
Pilot oil supply/drain Pilot oil supply for directional valve from port P2, external pilot oil drain for directional valve and ZDRE External pilot oil supply for directional valve, external pilot oil drain for directional valve and ZDRE Pilot oil supply for directional valve from P2, internal pilot oil drain for directional valve and external for ZDRE XL = Pilot oil supply from P2 to X is plugged (direct operated directional valve needs no pilot oil), pilot oil drain of directional valve is plugged (direct operated directional valve needs no pilot oil drain), external pilot oil drain for ZDRE Note: If no pilot oil supply is provided on

the subplate, use sandwich plate

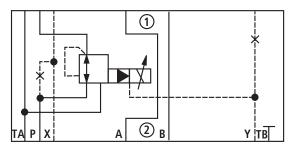
HSZ 10 B097-3X/M01 for the supply.

Symbols (1) = component side, 2) = plate side)

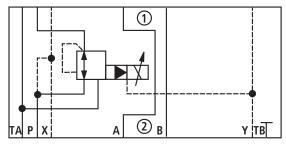
Type ZDRE



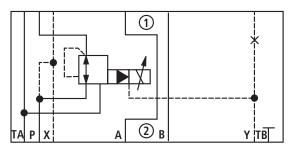
Type ZDRE10VP...XY



Type ZDRE10VP...XL

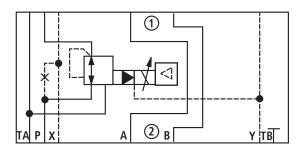


Type ZDRE10VP...Y

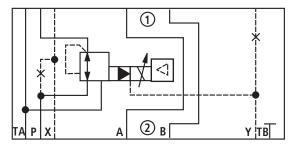


Type ZDRE10VP...L

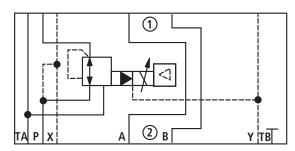
Type ZDREE



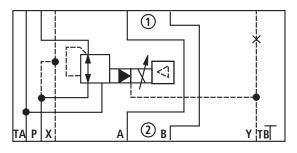
Type ZDREE10VP...XY



Type ZDREE10VP...XL

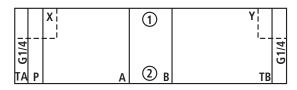


Type ZDREE10VP...Y



Type ZDREE10VP...L

Type sandwich plate HSZ



Sandwich plate HSZ 10 B097-3X/M01

- Dimensions (length x width x height): 100 x 70 x 30 mm
- Weight: 2.5 kg
- Size of ports X and Y: G1/4
- Dimensional sheet no.: R900262648

Function, section

Type ZDRE

Valves of type ZDRE... are pilot operated pressure reducing valves of sandwich plate design in 3-way variant, i.e. with pressure limitation of the actuator pressure.

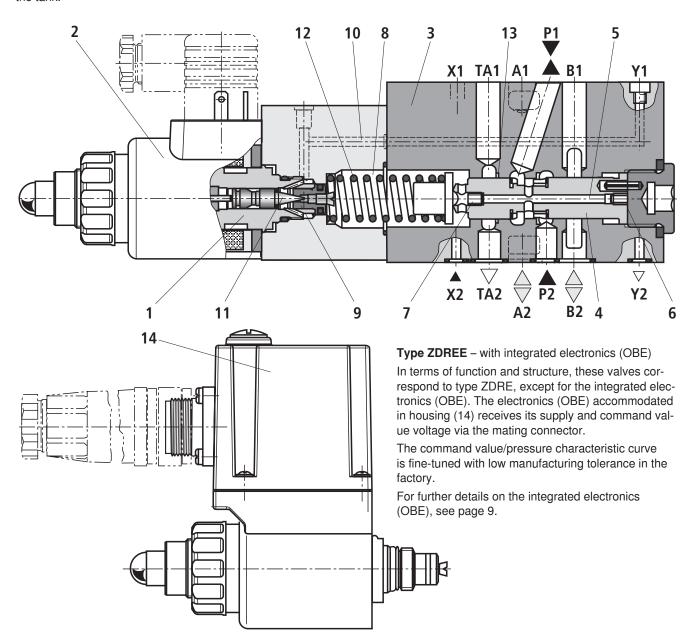
They are used for reducing a system pressure.

They basically consist of pilot part (1) with proportional solenoid (2), main valve (3) and control spool (4). The pressure in channel P1 is adjusted in dependence on the command value via proportional solenoid (2).

In the rest position, i.e. when no pressure is present in channel P2, control spool (4) opens the connection from channel P2 to P1.

The pressure in channel P1 acts via bore (5) onto spool area (6). The pilot oil for the pilot valve is taken from channel P1 and flows via bore (5), orifice (7), to spring chamber (8). From there, it is fed via valve seat (9), bore (10) and Y-line back to the tank.

The pressure required in channel P1 is pre-selected on the associated amplifier. The proportional solenoid moves valve poppet (11) towards valve seat (9) and increases the pressure in spring chamber (8). Thus, the pressure in both chambers (6) and (8) is balanced, and compression spring (12) pushes spool (4) to the right in the opening direction P2 to P1. As soon as actuator pressure P1 has increased to the value set on the pilot valve, valve poppet (11) opens and limits the pressure in spring chamber (8). Control spool (4) now moves to the left to the control position. When actuator pressure P1 exceeds the value set on the pilot valve, the control spool is pushed further to the left. It closes the connection from P2 to P1 and opens the connection P1 to tank TA1 at control land (13) until this pressure falls again to the set value.

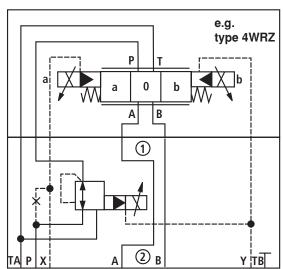


Pilot oil supply for directional valve mounted above

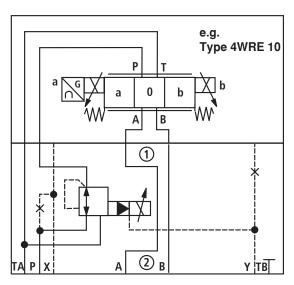
™ Notes

- On the direct operated directional valve, the seals for ports X and Y are missing on the connection faces of the housing. To prevent hydraulic fluid from flowing out, the pilot oil supply from P2 to X and the pilot oil drain between the directional valve and the ZDRE(E) must be plugged (variant XL).
- Leakage through the spool clearance from P to B can result in pressure building up in channel B!
- A pilot operated proportional directional valve in conjunction with the ZDRE(E) must have an external pilot oil supply.

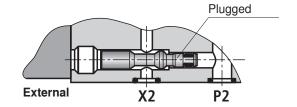
On variants XY and XL the connection between P2 and X is plugged.



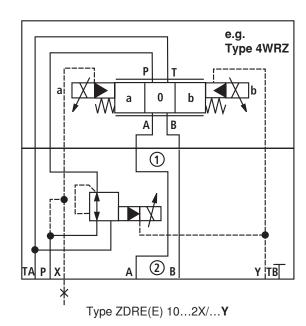
Type ZDRE(E) 10...2X/...XY



Type ZDRE(E) 10...2X/...XL



On variants Y and L port X must be plugged on the subplate.

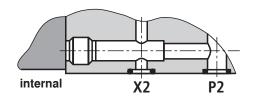


e.g. type 4WRZ

P T

A B

Type ZDRE(E) 10...2X/...L



Technical data (for applications outside these parameters, please consult us!)

General				
Weight	ZDRE	kg	5.1	
	ZDREE	kg	5.2	
Installation orientation			Preferred orientation of the proportional solenoid: pointing downwards or horizontal	
Storage temperature range °C		°C	-20 to +80	
Ambient	ZDRE	°C	-20 to +70	
temperature range	ZDREE	°C	-20 to +50	
Hydraulic (measure	d with HLP 46; $\vartheta_{oil} = 40$	0 °C ± 5	°C)	
Maximum operating	Port P1	bar	315 The pressure in an P2 must be about 20 bar higher	
pressure	Ports P2; A; B; X	bar	than the required set pressure, which is to be achieved in P1.	
	Port T	bar	250	
	Port Y or L		Line separately and at zero pressure to tank	
Maximum	Pressure rating 50 bar	bar	50	
set pressure in port P1	Pressure rating 100 bar	bar	100	
	Pressure rating 200 bar	bar	200	
	Pressure rating 315 bar	bar	315	
Min. set pressure in channel P1 with zero command value		bar	See $p_{\rm Emin}$ - $q_{\rm v}$ characteristic curve on page 12	
Permissible max. flow		l/min	80	
Pilot flow		l/min	0.6 to 0.9	
Hydraulic fluid			Mineral oil (HL, HLP) to DIN 51524, further hydraulic fluids on request	
Hydraulic fluid temperature range		°C	-20 to +80	
Viscosity range		mm²/s	15 to 380	
Permissible max. degree of contamination of the hydraulic fluid - cleanliness class to ISO 4406 (c)			Class 20/18/15 ¹⁾	
Hysteresis		%	±3 of maximum set pressure	
Repeatability		%	< ±2 of maximum set pressure	
Linearity	arity % ±3.5		±3.5 of maximum set pressure	
Manufacturing tolerance of command value/pres-	ZDRE ²⁾	%	±5 of set max. pressure	
sure characteristic curve, referred to hysteresis characteristic curve	ZDREE 3)	%	±1.5 of set max. pressure	
Step response $T_{\rm u}$ + $T_{\rm g}$	10 → 90%	ms	~160 Measured with 5 liters of a standing ~160 hydraulic fluid column in port P1	
	90 → 10%	ms		

¹⁾ The cleanliness classes specified for components must be adhered to in hydraulic systems. Effective filtration prevents malfunction and, at the same time, prolongs the service life of components.

For the selection of filters, see data sheets RE 50070, RE 50076, RE 50081, RE 50086 and RE 50088.

²⁾ For details, see page 10

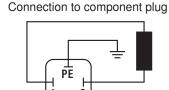
³⁾ Adjustment in the factory

Technical data (for applications outside these parameters, please consult us!)

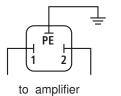
Electrical				
Minimum solenoid current		mA	100	
Maximum solenoid current m/		mA	1600 ± 10 %	
Solenoid coil resistance	Cold value at 20 °C	Ω	5.5	
	Max. warm value	Ω	8.05	
Duty cycle		%	100	
Electrical, integrate	ed electronics (OBE)			
Supply voltage	Nominal voltage	VDC	24	
	Lower limit value	VDC	21	
	Upper limit value	VDC	35	
Current consumption		Α	≤ 1.5	
Required fuses		А	2, slow-blowing	
Inputs	Voltage	V	0 to 10	
	Current	mA	4 to 20	
Output	Actual current value	mV	1 mV ≙ 1mA	
Type of protection of the valve to EN 60529			IP 65 with mating connector mounted and locked	

Electrical connection (dimensions in mm)

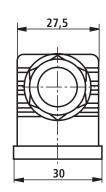
ZDRE

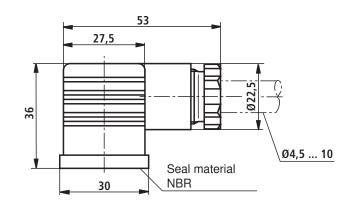


Connection to mating connector



Mating connector (black) to DIN EN 175301-803 Material no. **R901017011** (separate order)

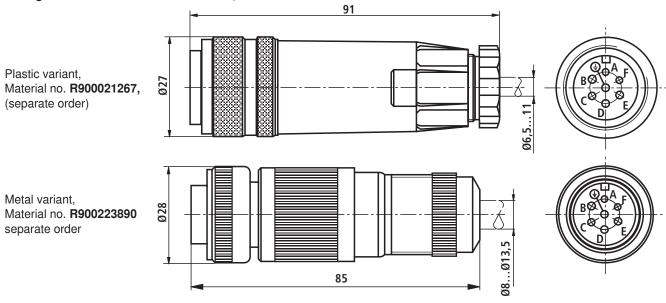




ZDREE

Component plug pinout	Contact	Pinout of interface "A1"	Pinout of interface "F1"	
Supply voltage	А	24 VDC (u(t) = 21 V to 35 V); $/_{max} \le 1.5 \text{ A}$		
	В	0 V		
Actual value reference potential	С	Reference contact F; 0 V Reference contact		
Differential amplifier input	D	0 to 10 V; R _i = 100 kΩ	4 to 20 mA; R_i = 100 Ω	
	Е	Command value reference potential		
Measurement output (actual	F	0 to 1.6 V actual value (1 mV ≜ 1 mA)		
value)	r	Load resistance > 10 k Ω		
	PE	Connected to solenoid and valve housing		

Mating connectors to DIN EN 175201-804, soldered contacts for cable cross-section 0.5 to 1.5 mm²

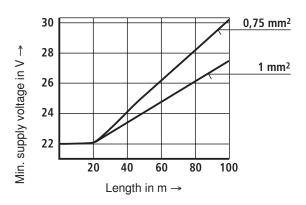


Electrical connection

Connection cable for ZDREE

- Recommendation: 6-wire, 0.75 or 1 mm² plus protective earth conductor and shield
- Connect shield only on the supply side to PE
- Permissible max. length 100 m

The minimum supply voltage on the power supply unit depends on the length of the supply cable (see diagram).



Integrated electronics (OBE) of type ZDREE

Function

Power supply to electronics via connections A and B. The command value is applied to differential amplifier connections D and E.

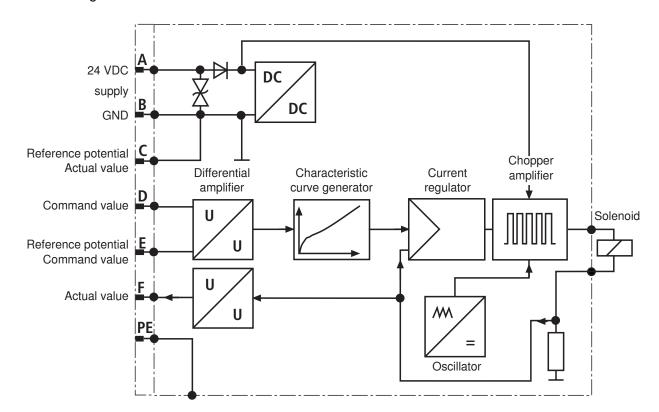
The characteristic curve generator adapts the command value/solenoid current characteristic curve to the valve so that non-linearities in the hydraulics are compensated for and a linear command value/pressure characteristic curve is obtained.

The current regulator regulates the solenoid current independently of the solenoid coil resistance.

A chopper amplifier with a clock frequency of ca. 180 Hz to 400 Hz forms the power output stage of the electronics for controlling the proportional solenoid. The output signal is pulse-width-modulated (PWM).

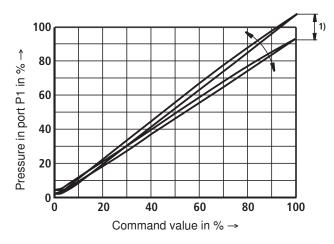
For testing the solenoid current, a voltage, which is proportional to the solenoid current, can be measured between pin F(+) and pin C(-) on the plug-in connector. **1 mV** corresponds to a solenoid current of **1 mA**.

Block circuit diagram



Characteristic curves (measured with HLP46, ϑ_{oil} = 40 °C ± 5 °C)

Reduced pressure in port P1 in dependence upon the command value (manufacturing tolerance)

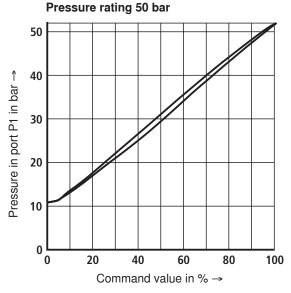


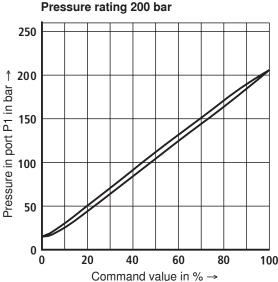
1) For valve ZDRE the tolerance can be modified on the external amplifier (for type and data sheet, see page 2) using command value attenuator potentiometer "Gw". The digital amplifier can be adjusted by means of parameter "Limit".

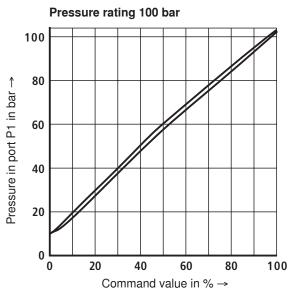
Here, the control current specified in the technical data must not be exceeded.

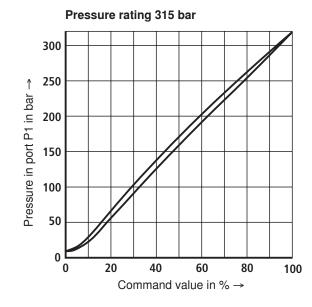
In order that several valves can be matched to the same characteristic curves, the pressure at a command value of 100 % must not be set higher than the maximum pressure setting of the pressure rating.

Pressure in port P1 in dependence upon the command value (at flow 0 l/min)



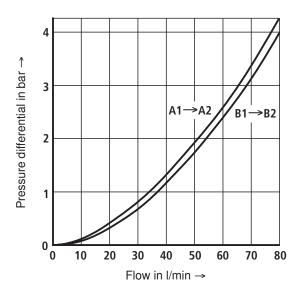


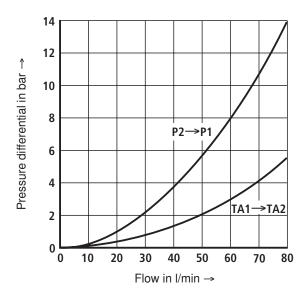




Characteristic curves (measured with HLP46, ϑ_{oil} = 40 °C ± 5 °C)

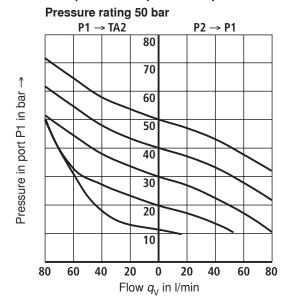
Pressure differential in dependence upon the flow



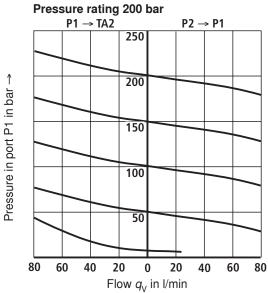


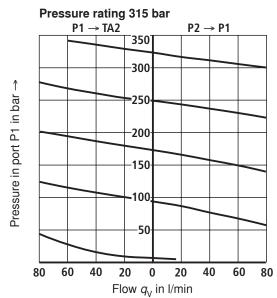
Characteristic curves (measured with HLP46, ϑ_{oil} = 40 °C ± 5 °C)

Pressure in port P1 in dependence upon the flow

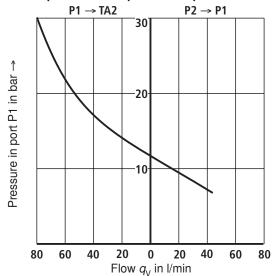


Pressure rating 100 bar $P1 \rightarrow TA2$ $P2 \rightarrow P1$ 140 120 Pressure in port P1 in bar 100 80 60 40 20 80 60 20 0 20 80 Flow q_V in I/min

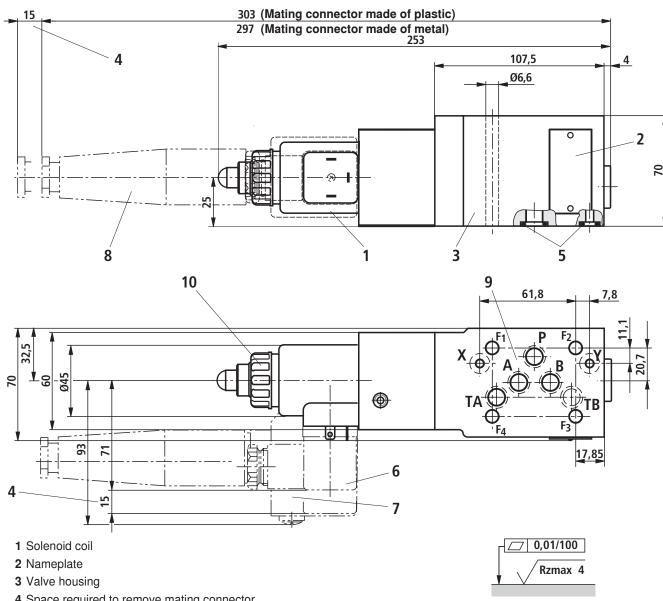




Min. set pressure in dependence upon the flow at zero command value



Unit dimensions (dimensions in mm)



- 4 Space required to remove mating connector
- 5 Identical seal rings for ports A2, B2, P2, TA2, TB2 Identical seal rings for ports X2, Y2
- 6 Mating connector for type ZDRE (separate order)
- 7 Integrated electronics (type ZDREE) with component plug
- 8 Mating connector for type ZDREE, plastic or metal variant, (separate order)
- 9 Porting pattern to DIN 24340-A10 and ISO 4401-05-05-0-05 (X, Y as required)
- 10 O-ring and plastic nut A/F 32 for coil mounting The nut can be loosened by turning it counter-clockwise (1 turn). The solenoid coil can then be rotated to the desired position and fixed by tightening the nut. Tightening torque: 4+1 Nm

Valve mounting screws

4 hexagon socket head cap screws ISO 4762-M6-10.9-flZn-240h-L (Friction coefficient $\mu_{\text{total}} = 0.09 \text{ to } 0.14$); tightening torque $M_{\rm T}$ = 12.5 Nm ± 10 %

Required surface quality

of valve mounting face

4 hexagon socket head cap screws ISO 4762-M6-10.9 (Friction coefficient $\mu_{\rm total}$ = 0.12 to 0.17); tightening torque $M_{\rm T}$ = 15.5 Nm ± 10 % Screw length as required

Notes

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